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With the ability to accomplish a variety of jobs, such as welding, surgery, assembly, cleaning, and more, the Robotics and Automation Handbook provides a solid foundation for engineers and scientists interested in designing, fabricating, or utilizing robotic systems. It targets issues related to determining the specifications and configurations for developing an actual robot and discusses how a robot is controlled using a variety of controls in terms of trajectory and input signals it needs. The book explains the ways a robot is, how it "senses" the external world, and how design and fabrication are affected by application needs.