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Serving as the first comprehensive reference on this interdisciplinary technology, *Autonomous Mobile Robots* authoritatively addresses the theoretical, technical, and practical aspects of the field. The book examines in detail the key components that form an autonomous mobile robot, from sensors and sensor fusion to modeling and control, map building and path planning, and decision making and autonomy, and to the final integration of these components for diversified applications. Expert contributors share hard-won insight into the practical implementation and integration issues involved in developing autonomous and open robotic systems and include examples, illustrations, and applications.