

Librería

Bonilla y Asociados

desde 1950



Título:

Autor:

Precio: \$848.46

Editorial:

Año: 2009

Tema:

Edición: 1^a

Sinopsis

ISBN: 9780821844250

The work treats dynamical systems given by ordinary differential equations in the form $\frac{dX^\varepsilon}{dt} = \varepsilon B(X^\varepsilon, Y^\varepsilon)$ where fast motions Y^ε depend on the slow motion X^ε (coupled with it) and they are either given by another differential equation $\frac{dY^\varepsilon}{dt} = b(X^\varepsilon, Y^\varepsilon)$ or perturbations of an appropriate parametric family of Markov processes with freezed slow variables.

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